
Circulation et hélicité cinétique sous la photosphère solaire et leur relation avec l'activité magnétique de surface

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Global Helioseismology

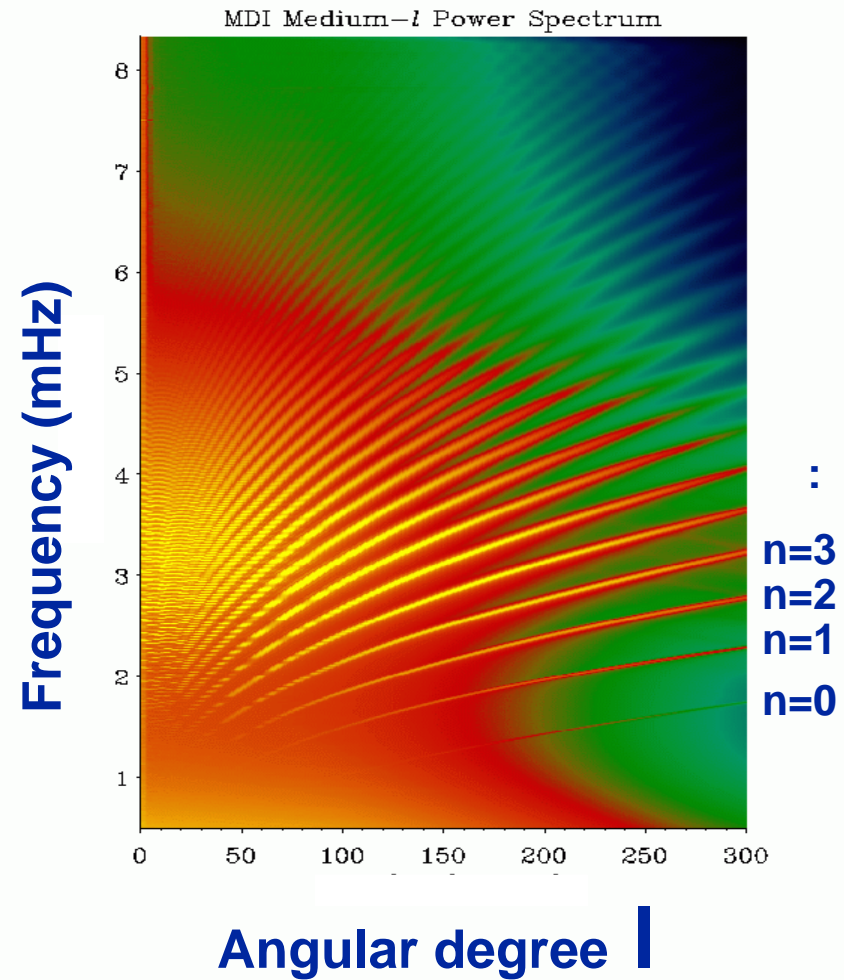
Internal Rotation breaks spherical symmetry

=> Multiplets of $2l+1$ frequencies

$$\frac{\omega_{nl-m} - \omega_{nlm}}{m} = \iint K_{nlm}(r, \theta) \Omega(r, \theta) dr d\theta$$

\uparrow
observed
 \uparrow
Standard Solar Model
 \uparrow
Unknown

=> 2D Inverse Problem



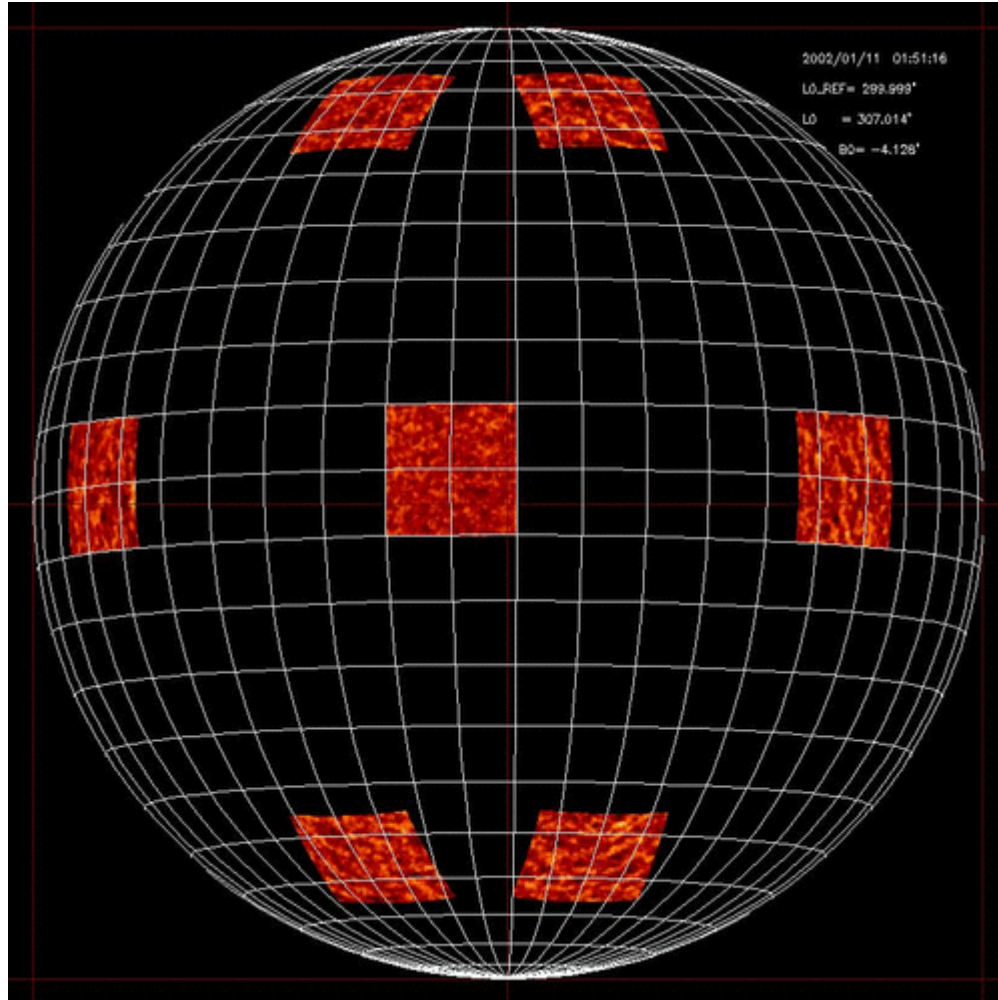
Global Helioseismology

Limitations

- ❑ Sensitive only to the part of the rotation that is symmetric about the equator.
- ❑ Kernels Independent of longitude (e.g. cannot detect effect of active region on rotation)
- ❑ Limited access to the polar zone
- ❑ Impossible to separate the spherically asymmetric effects other than rotation (meridional circulation, magnetic fields, structural asphericity)

Local Helioseismology

Analysis Principles



- Small areas ($16^\circ \times 16^\circ$) are **tracked** (typically between 8hrs and 28hrs) over the solar disk at a rate depending on the latitude of their center.
- These areas are **remapped** using a **Postel** or **transverse cylindrical projection** that tend to preserve the distance along great circles.
- => Data cubes
(Latitude – Longitude – time)

Local Helioseismology

Main Methods

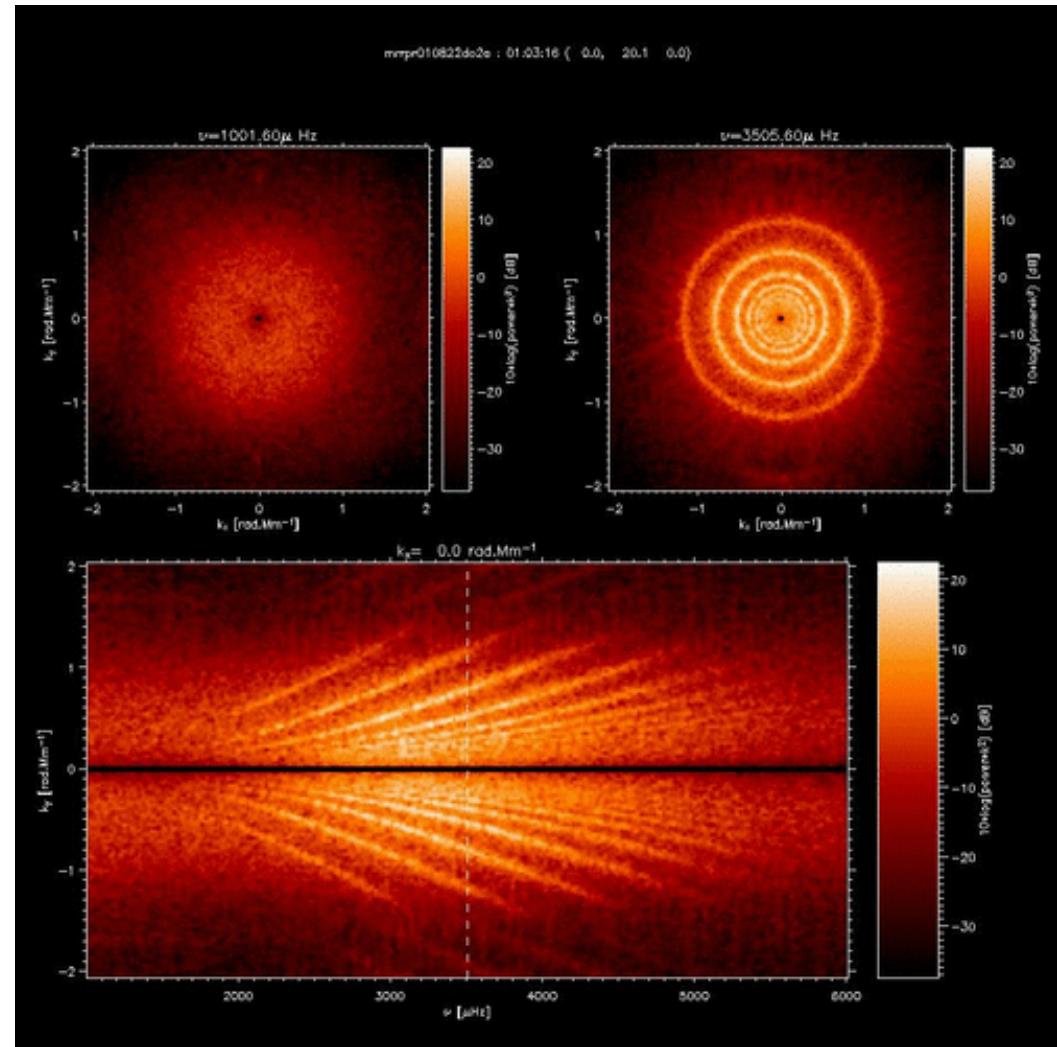
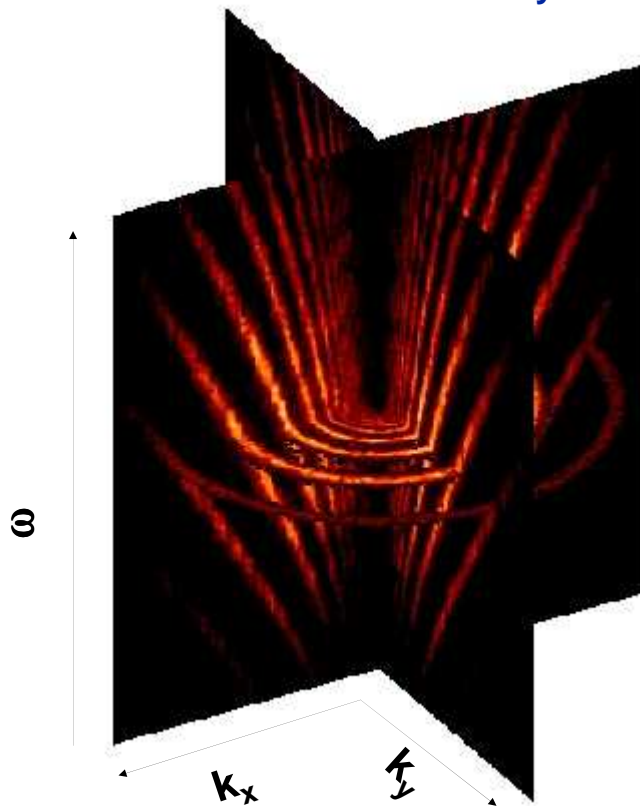
Based on the local observation of global acoustic modes.

- 1. Ring-Diagram analysis (Fourier domain)**
(Gough & Toomre 1983; Hill 1988)
- 2. Time-distance analysis (Time domain)**
(Duvall et al. 1993, 1996)
- 3. Acoustic Holography (Phase sensitive)**
(Lindsey & Braun, 1990, 1997)

Ring Diagram Analysis

3D FFT

$$(\theta, \varphi, t) \rightarrow (k_x, k_y, \omega)$$



Ring Diagram Analysis

3D FFT



3D Power spectra Fitting

$(\theta, \varphi, t) \rightarrow (k_x, k_y, \omega)$

$$P = \frac{A}{(\omega - \omega_0 + k_x U_x + k_y U_y)^2 + \Gamma^2} + \frac{b_0}{k^3}$$

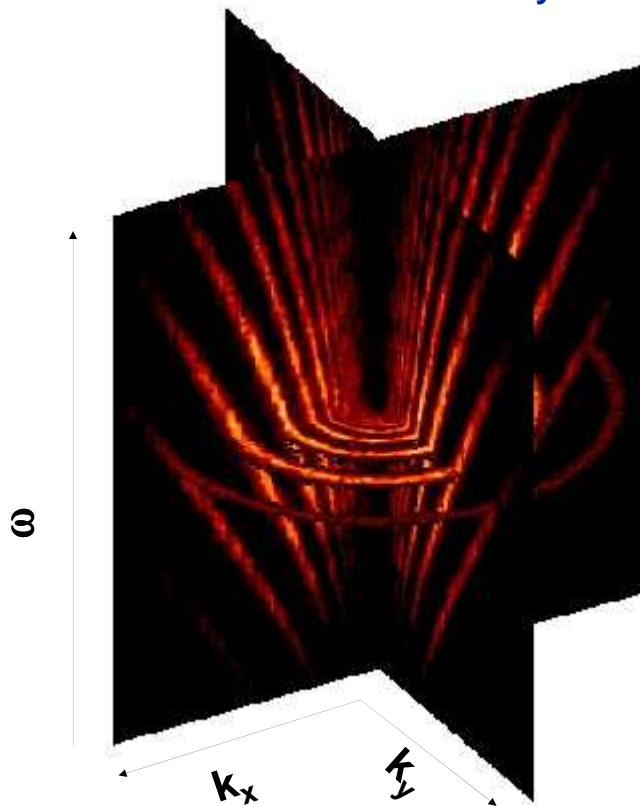


2 x 1D Inversions

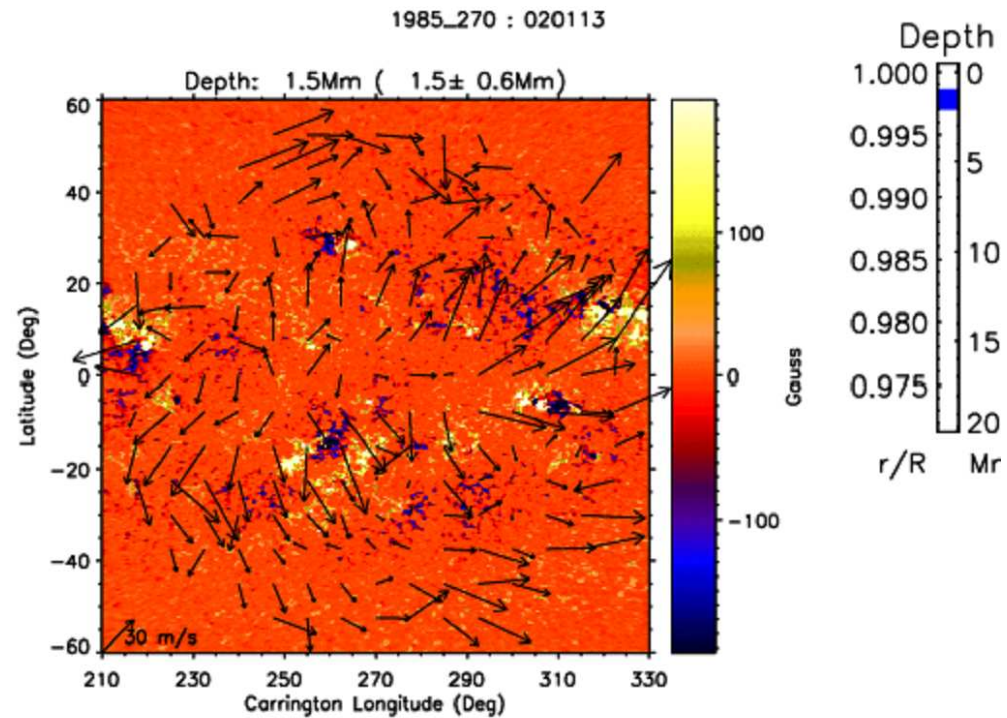
$$U_{x,y}(\omega_o, k_h) = \int K(\omega_o, k_h, z) v_{x,y}(z) dz$$

V_z may then be computed using the divergence of the horizontal flow and assuming mass conservation.

(Komm, Corbard et al. 2004)

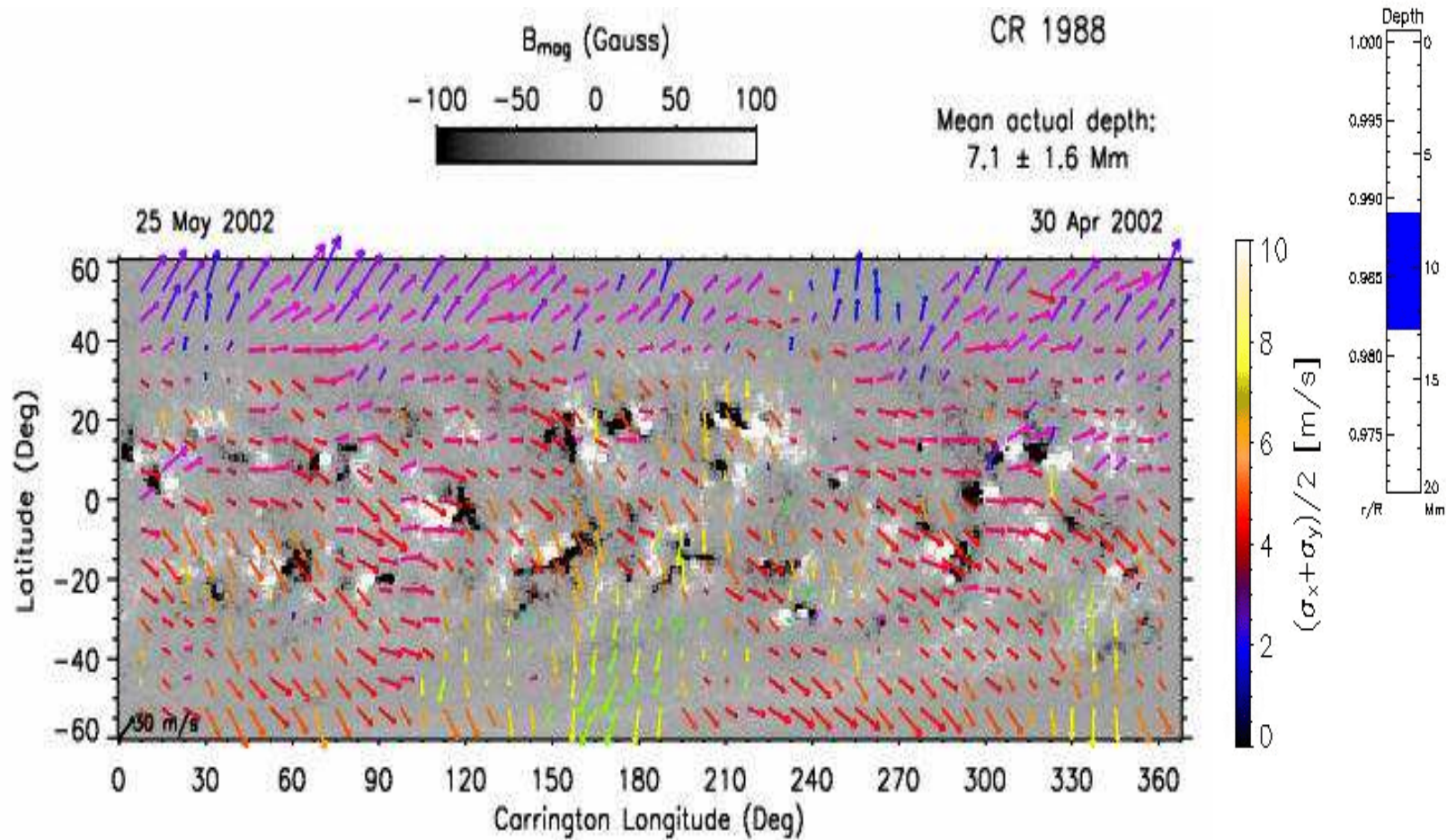


1664 mn « days » flow maps



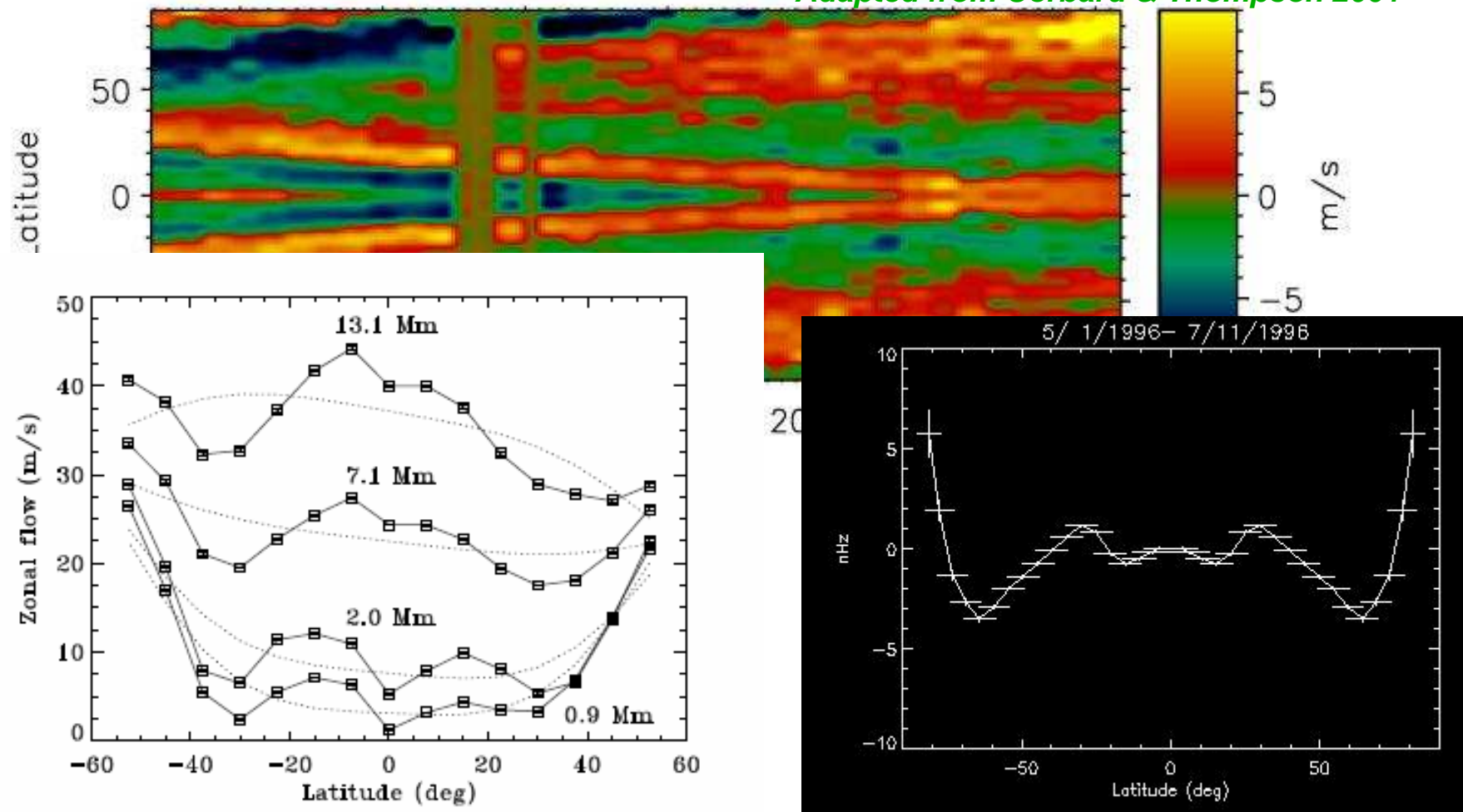
Ring Diagram Analysis

Synoptic Flow Maps



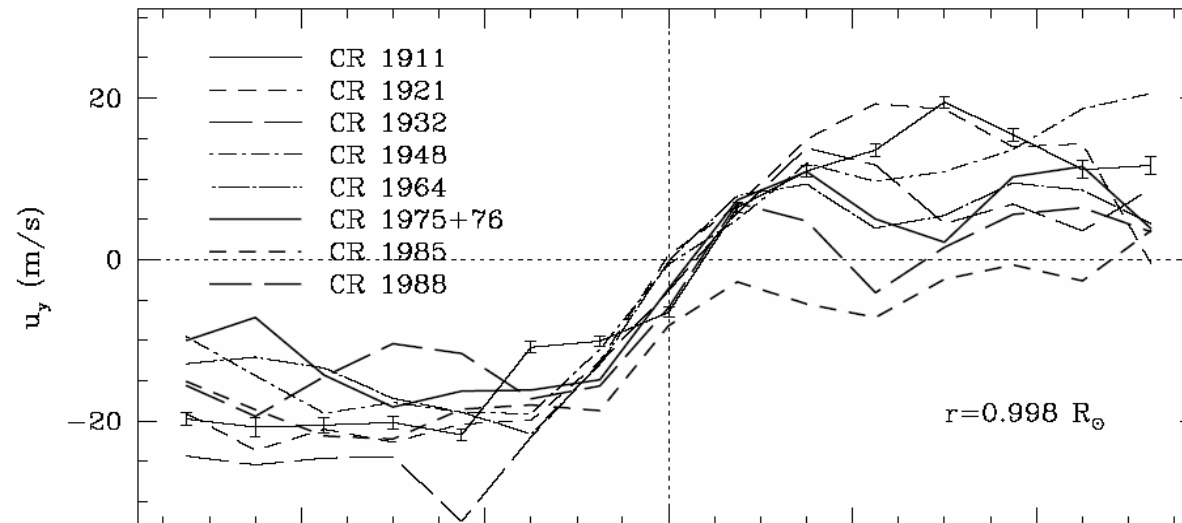
Averaged Zonal Flow residuals: Torsional Oscillations

Adapted from Corbard & Thompson 2001

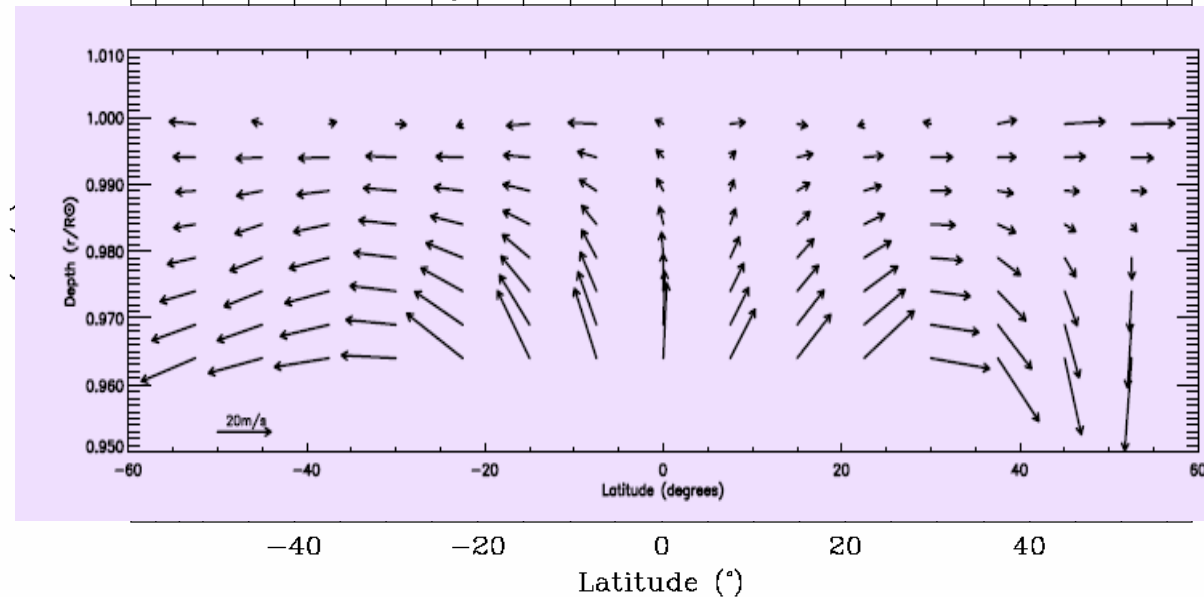


Time and depth variations of Meridional Flows

*Basu &
Antia 2002*



*Gonzalez
Hernandez et al.
2004*



Some fluid descriptors

From the daily flow maps, we calculate the divergence of the horizontal flow components and the vertical vorticity component

$$\text{div } v = \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} \quad (1)$$

$$\text{vort } v = \frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \quad (2)$$

where v_x is the zonal and v_y is the meridional flow component. We use $\text{div } v$ and $\text{vort } v$ to distinguish the components from the complete divergence ($\nabla \cdot \vec{v}$) and vorticity ($\nabla \times \vec{v}$). We then calculate synoptic maps of these quantities in the same way as for the velocities. In addition, we calculate the vertical gradients, $\partial v_x / \partial z$ and $\partial v_y / \partial z$, of the horizontal flow components and the corresponding synoptic maps. All quantities are functions of latitude, longitude, and depth.

Kinetic Helicity

The kinetic helicity of a fluid flow is the integrated scalar product of the velocity field, \vec{v} , and the vorticity field, $\nabla \times \vec{v}$ (Moffatt & Tsinober 1992):

$$\mathcal{H} = \int \vec{v} \cdot \nabla \times \vec{v} \, dV \quad (7)$$

where $\vec{v} \cdot \nabla \times \vec{v}$ is called the helicity density of the flow. The kinetic helicity and its density are pseudoscalar quantities. If the vorticity is a stationary random quantity (for example, homogeneous turbulence), one can define the mean helicity

$$H = \langle \vec{v} \cdot \nabla \times \vec{v} \rangle \quad (8)$$

Computing V_z using the continuity equation

Using the continuity equation (representing mass conservation), we estimate the vertical velocity component from the measured divergence of the horizontal flow (Scorer 1978; Holton 1979). The continuity equation can be written as follows

$$\cancel{\frac{\partial \rho}{\partial t}} + \nabla \rho \cdot \vec{v} + \rho \cdot \nabla \vec{v} = 0 \quad (3)$$

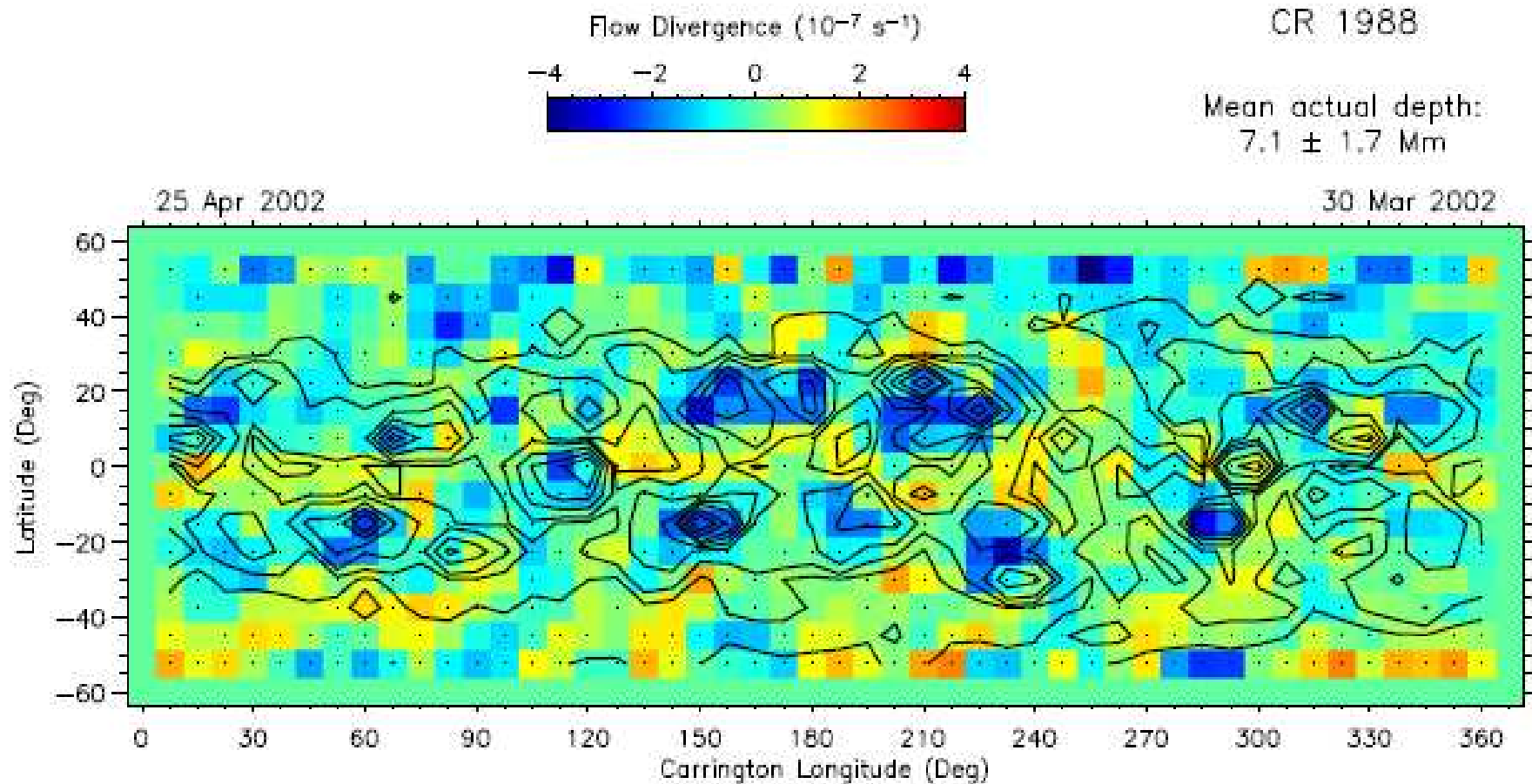
where ρ is the density and \vec{v} is the 3-dimensional velocity vector. Since each data point represents an average over 1664 minutes, we neglect the term of the temporal density fluctuations. In addition, we assume that any horizontal density variations average out over the area of a dense-pack patch. The density is simply a function of radius. The continuity equation can then be simplified to

$$\frac{\partial v_z}{\partial z} + \left(\frac{1}{\rho} \frac{\partial \rho}{\partial z} \right) v_z + \text{div } v = 0 \quad (4)$$

where $\text{div } v$ is the horizontal flow divergence (Equation 1). This equation has the following solution:

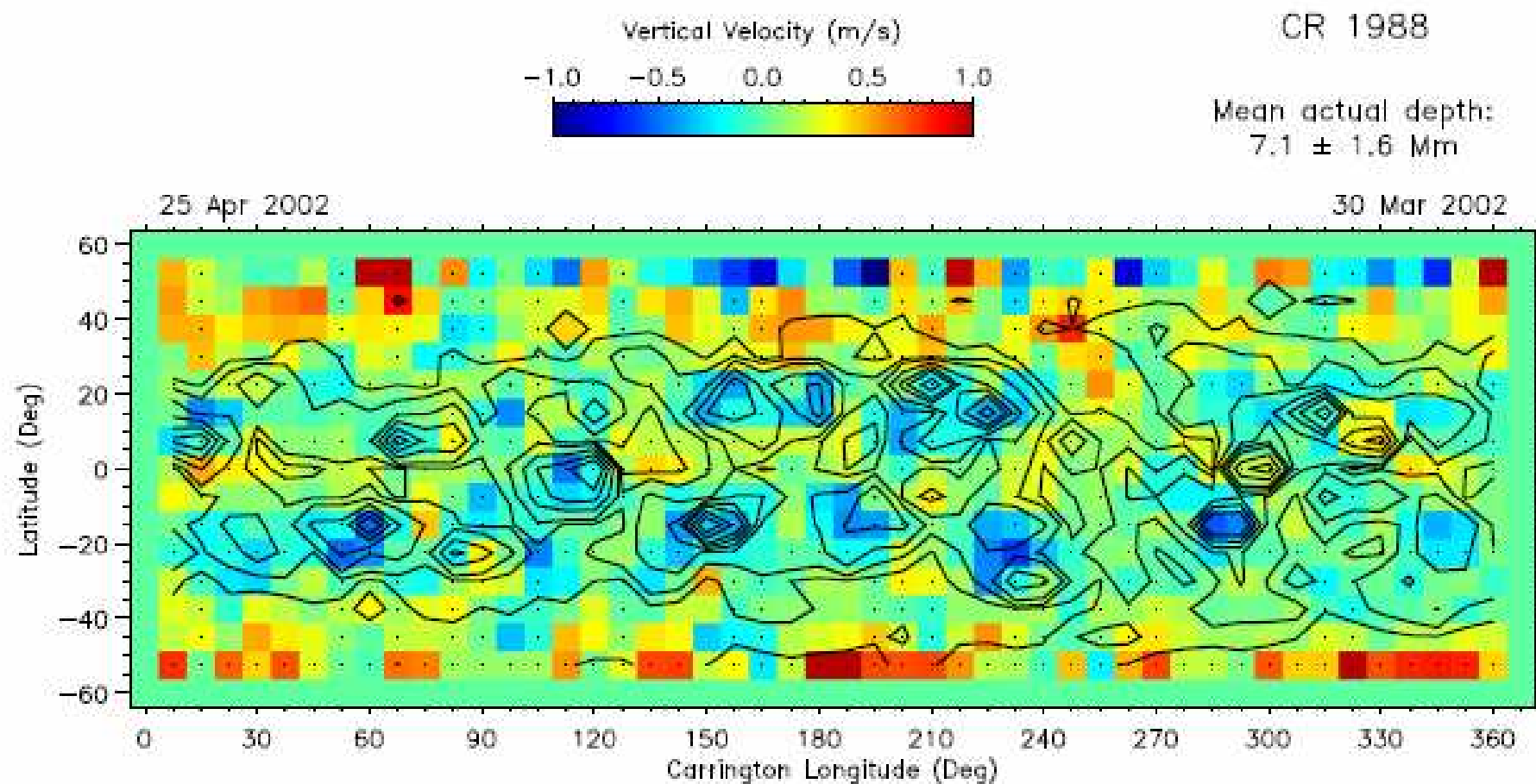
$$v_z(d) = -\frac{1}{\rho} \int_{R_\odot}^{R_\odot-d} \rho \text{ div } v \, dz + \cancel{\frac{\rho_\odot}{\rho}} \quad (5)$$

Divergence of horizontal flow (div v)



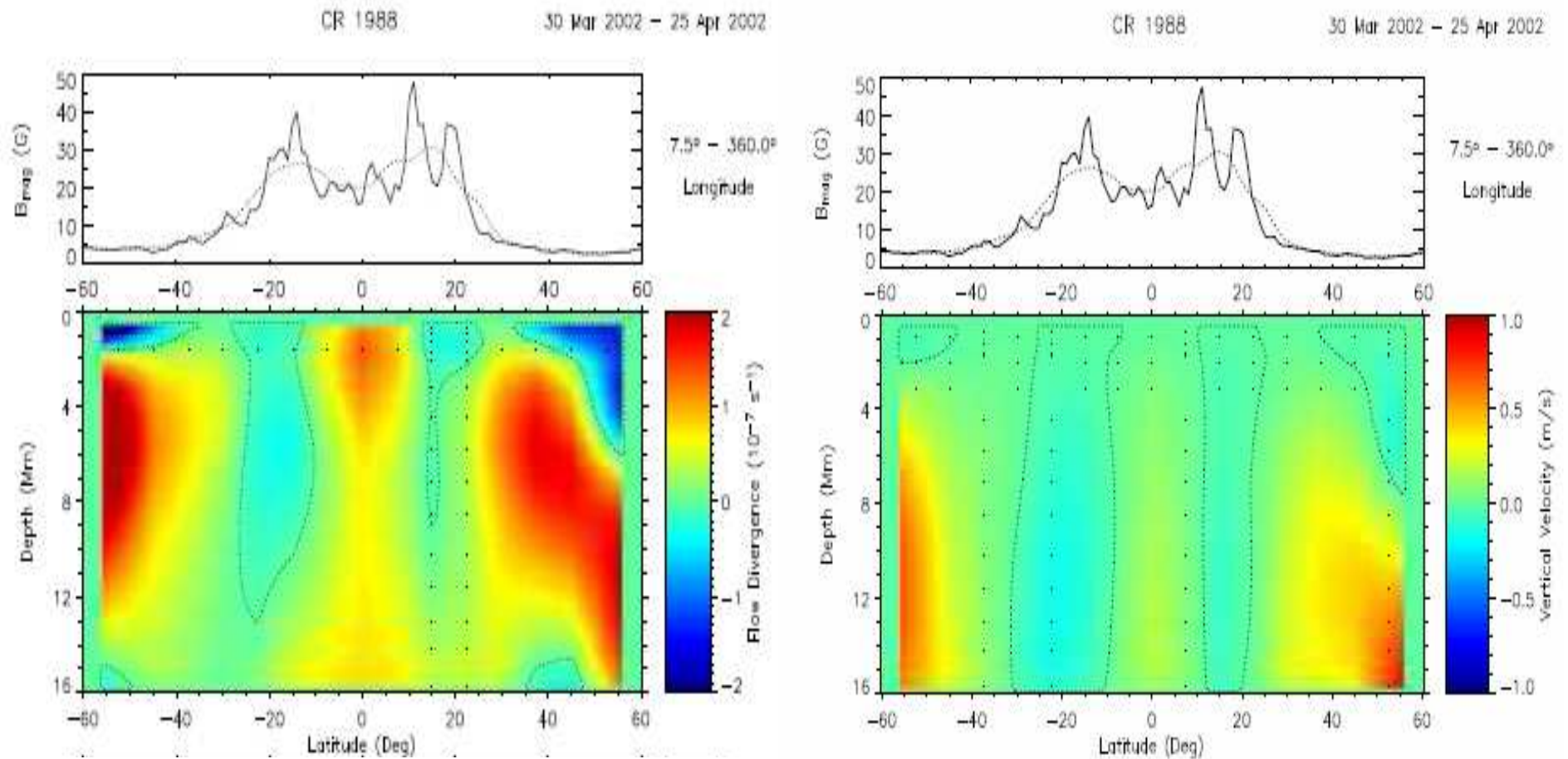
Komm, Corbard et al. 2004 (ring diagrams)

Vertical Velocity (V_z)



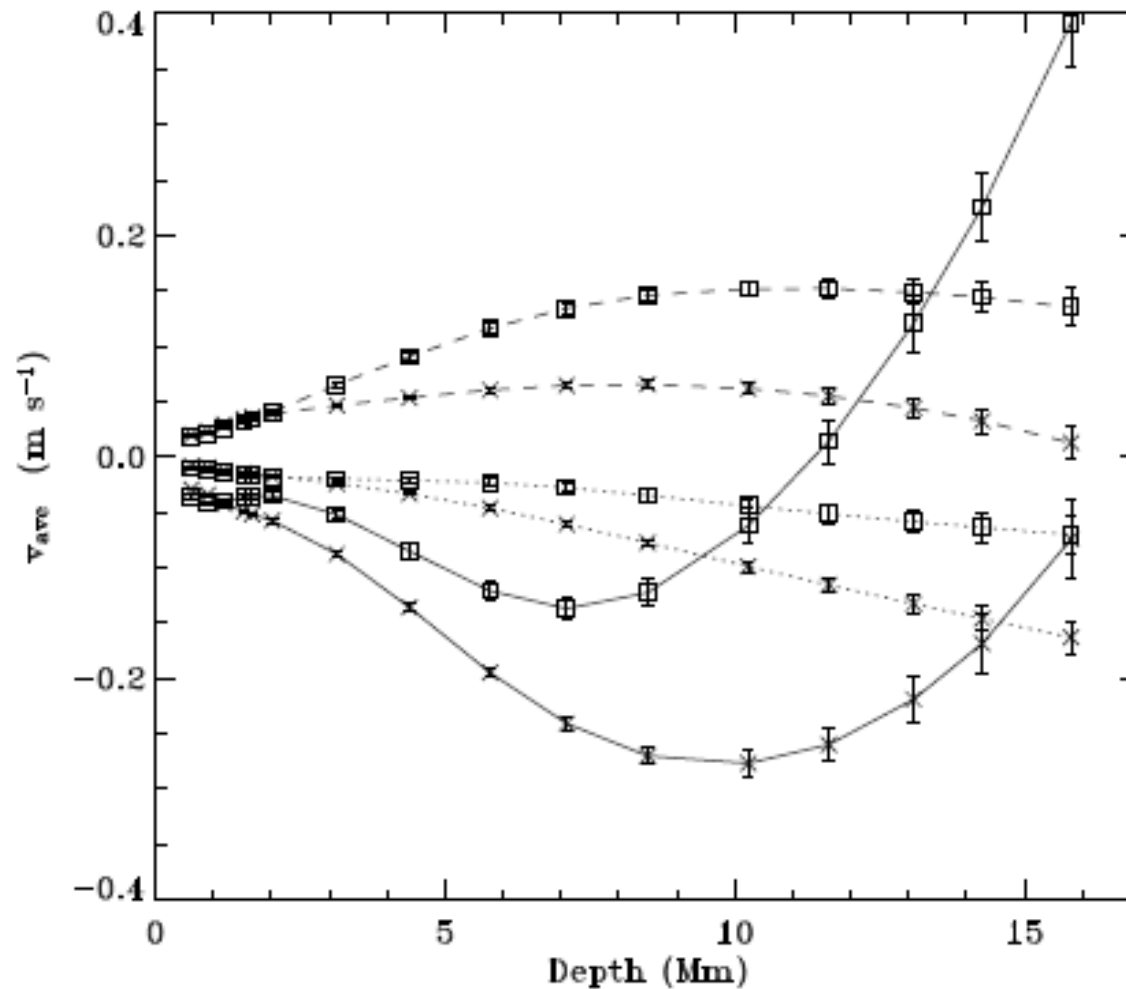
Komm, Corbard et al. 2004 (ring diagrams)

Div v / Vz as a function of depth



Komm, Corbard et al. 2004 (ring diagrams)

Vertical Velocity as a function of depth for 3 levels of magnetic activity



•Low B => up flows

•Medium B => Down flows

•High B => Down flows <10Mm
Up flows >10Mm

Selection of areas with different magnetic flux levels over 14 Carrington Rotations

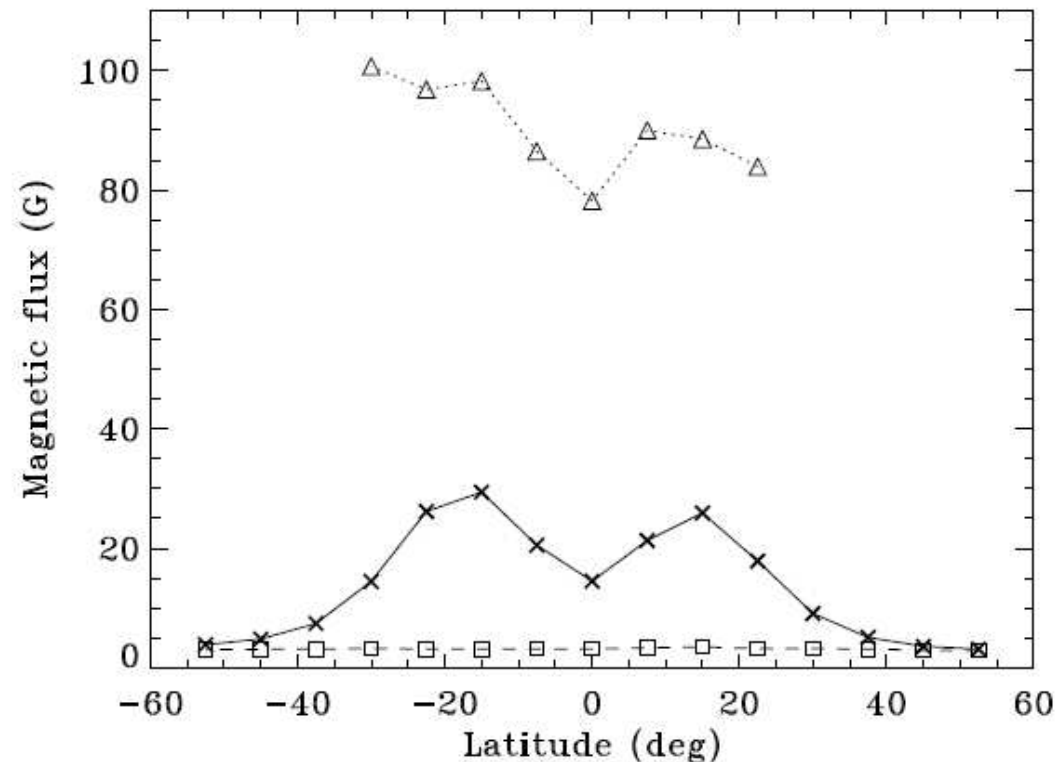
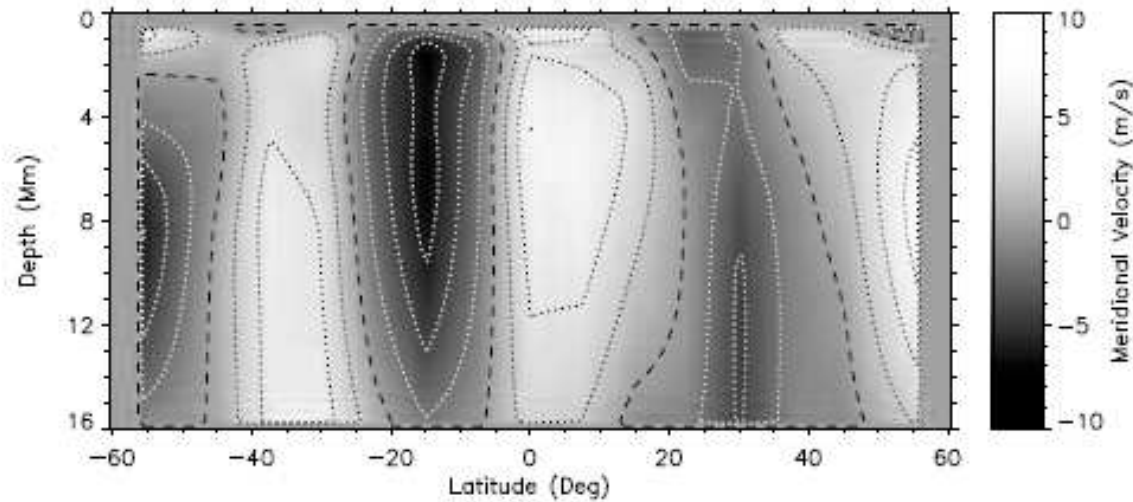
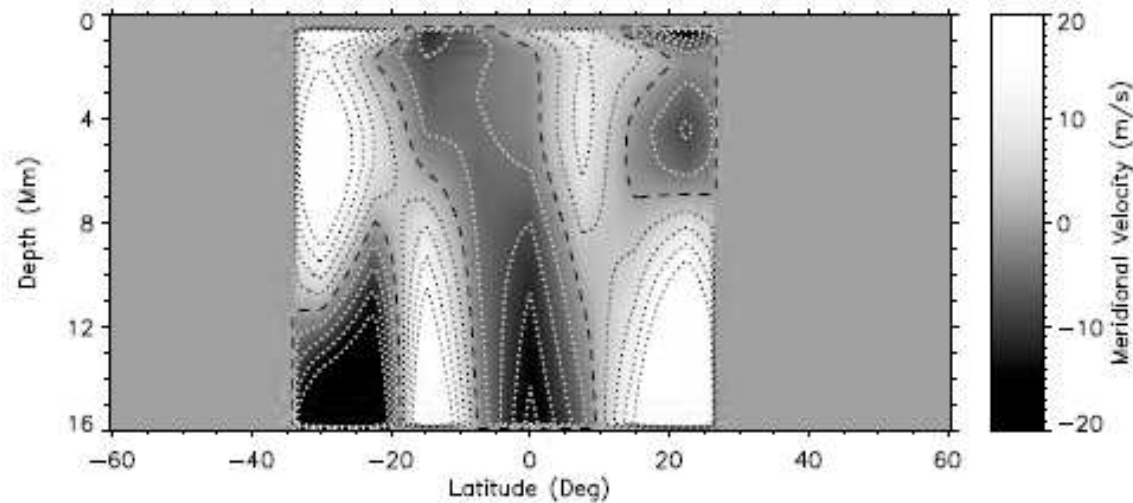


Fig. 1.— The magnetic flux as a function of latitude (solid line, cross symbols) averaged in longitude over CR 1979–1992 (2001, July 27 – 2002, Aug 12). The triangle symbols (dotted line) indicate the average over all locations with magnetic flux greater 71 G and the square symbols (dashed line) indicate the average over 25% of locations with the lowest flux.

Residual Meridional Flow V_y averaged over 14 CR

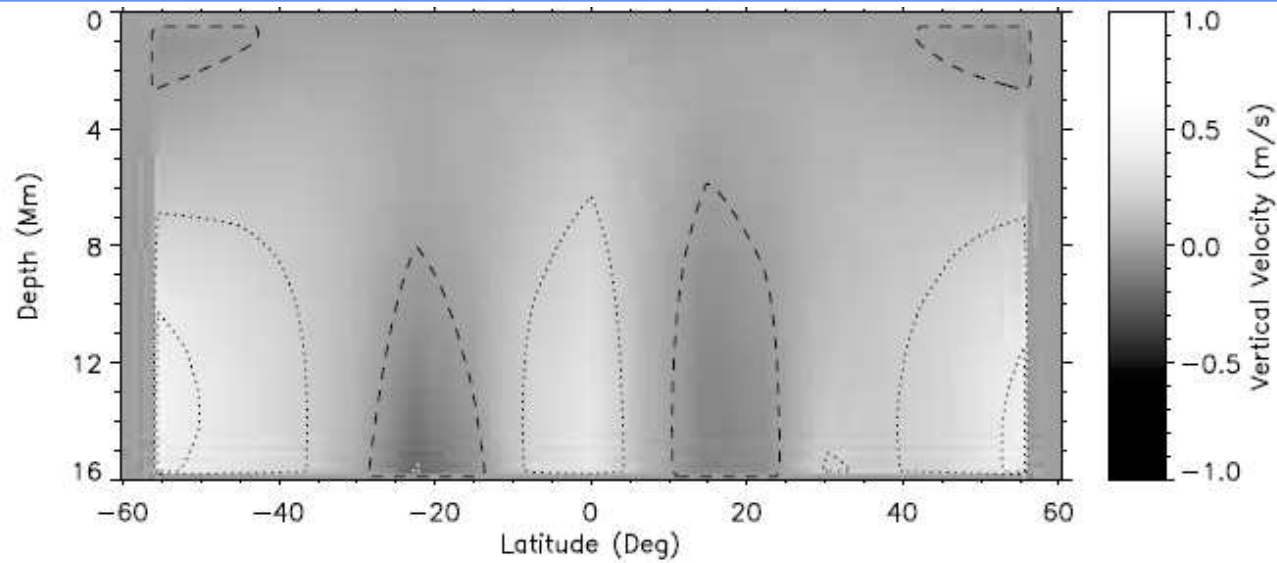


Low activity set

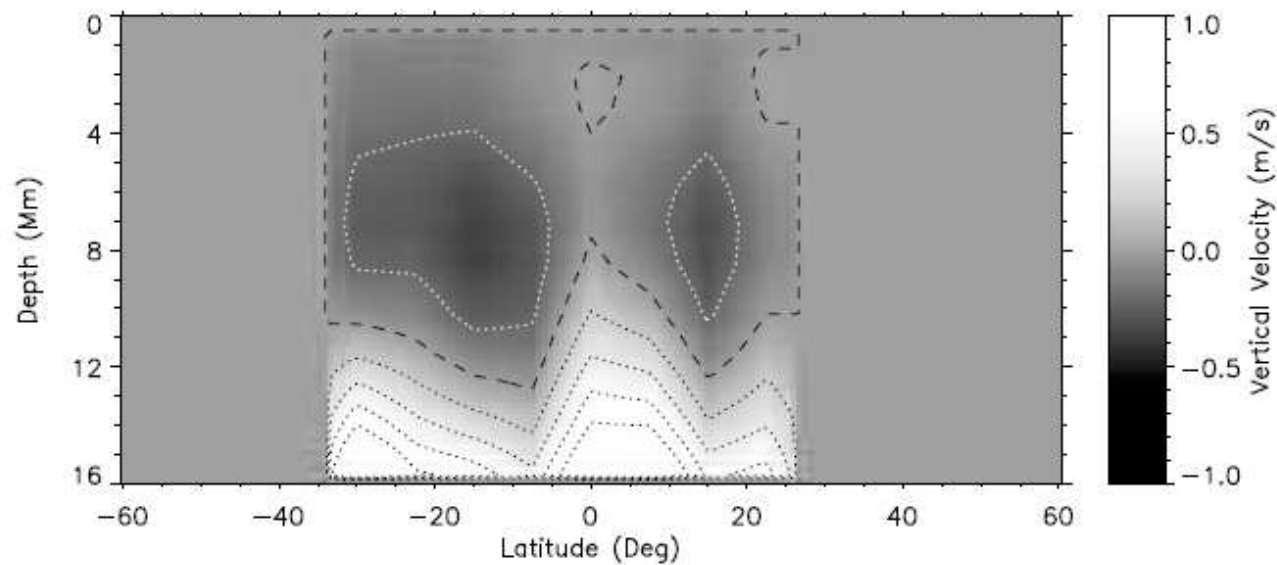


High activity set
 $B > 71$ G

V_z averaged over 14 CR

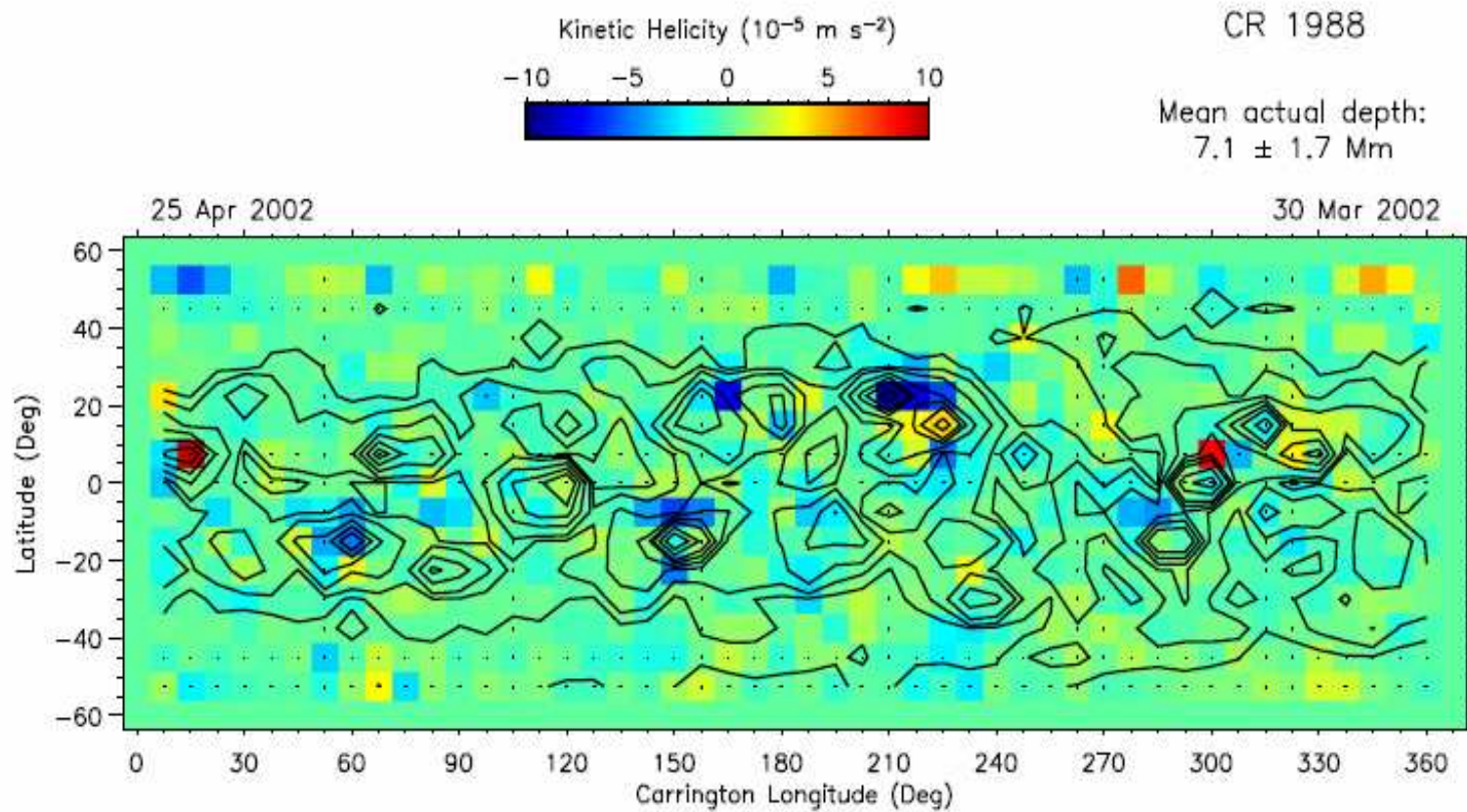


Low activity set

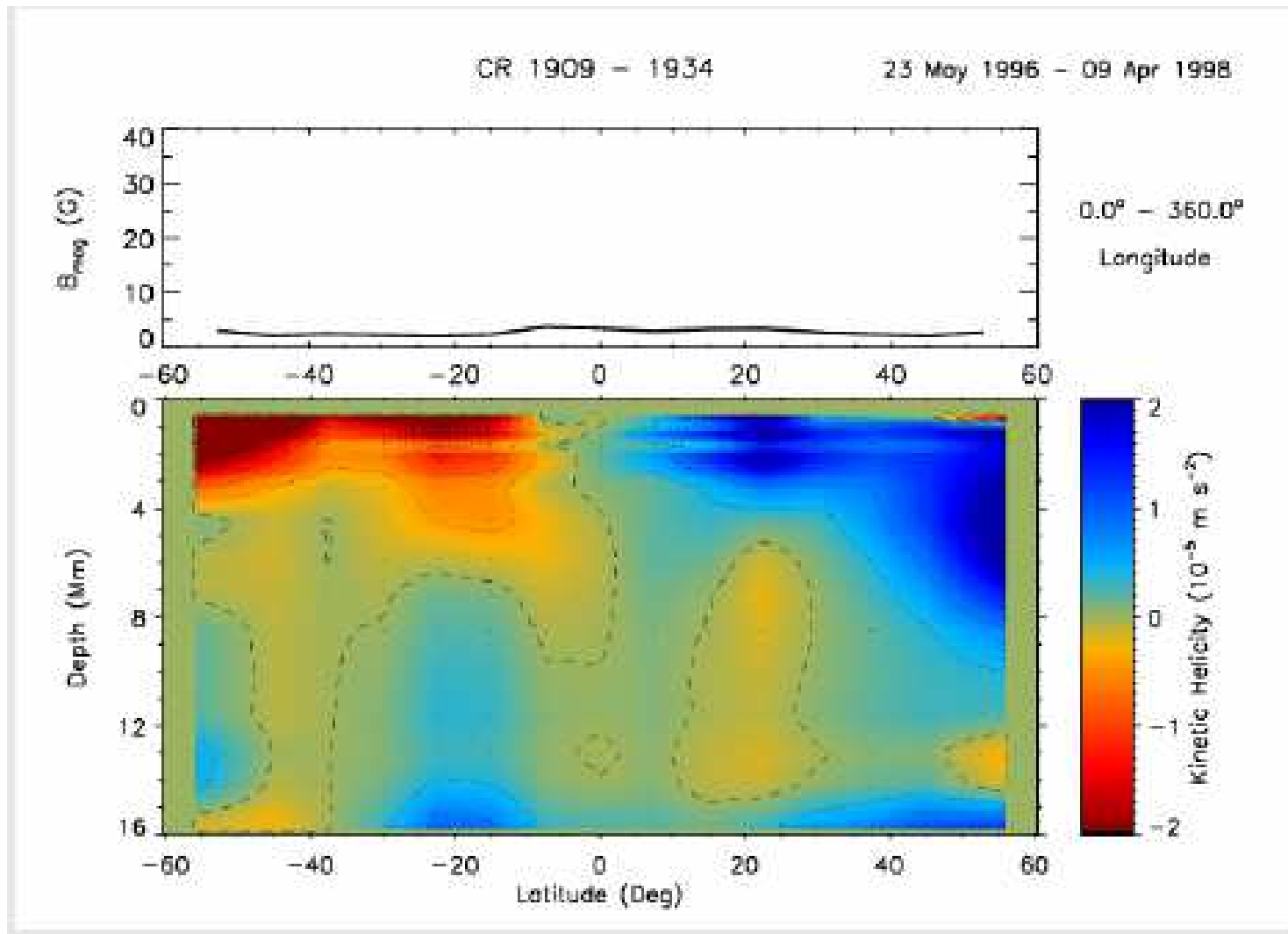


High activity set
 $B > 71$ G

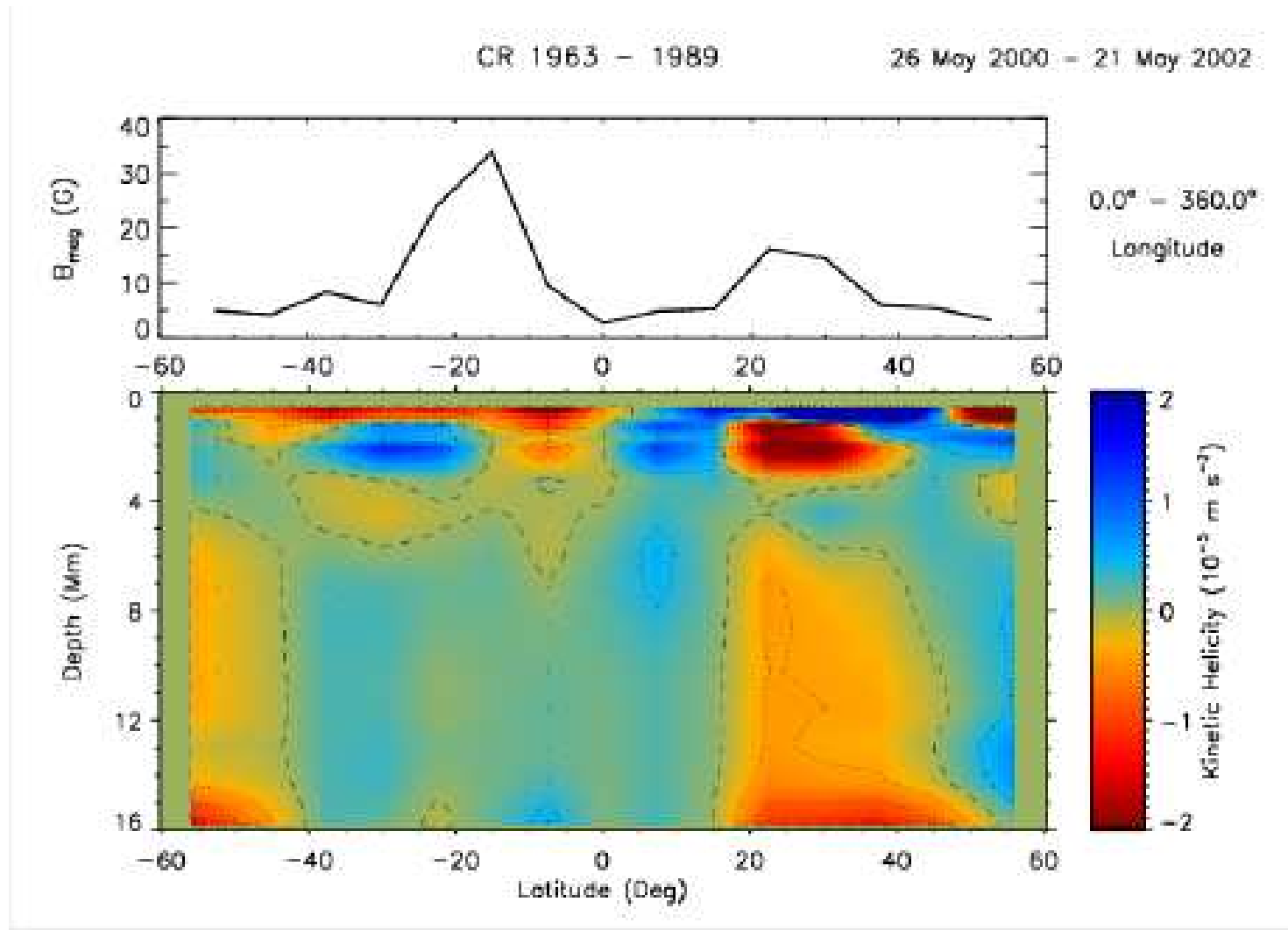
Synoptic Maps of Kinetic Helicity



Kinetic Helicity at low activity level



Kinetic Helicity at high activity level

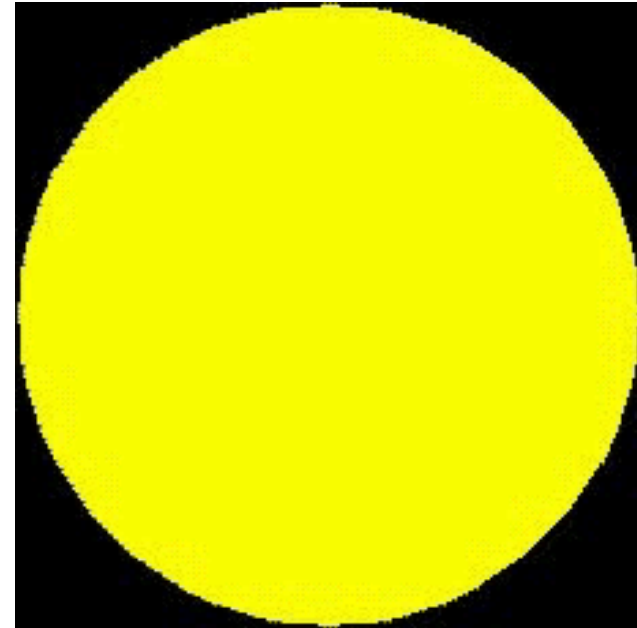


Time-distance helioseismology

Principles

- ❑ First developed by *Duvall 1993*
- ❑ Employs **waves travel times** observed between different surface location on the Sun.
- ❑ These travel times are then “inverted” to deduce:
 - Flow speed and direction,
 - Sound speed perturbations
 - [Magnetic field perturbations]

Along the ray paths of the observed modes.



Time-distance helioseismology

Interpretation of travel time perturbations

Dispersion relation:

(Kosovichev et al. 1997)

$$(\omega - \vec{k} \cdot \vec{v})^2 = \omega_{ac}^2 + \frac{k^2}{2} \left(c^2 + c_A^2 + \sqrt{(c^2 + c_A^2)^2 - 4c^2 (\vec{k} \cdot \vec{c}_A)^2 / k^2} \right)$$

3D velocity field

Acoustic cut off frequency

Alvén velocity

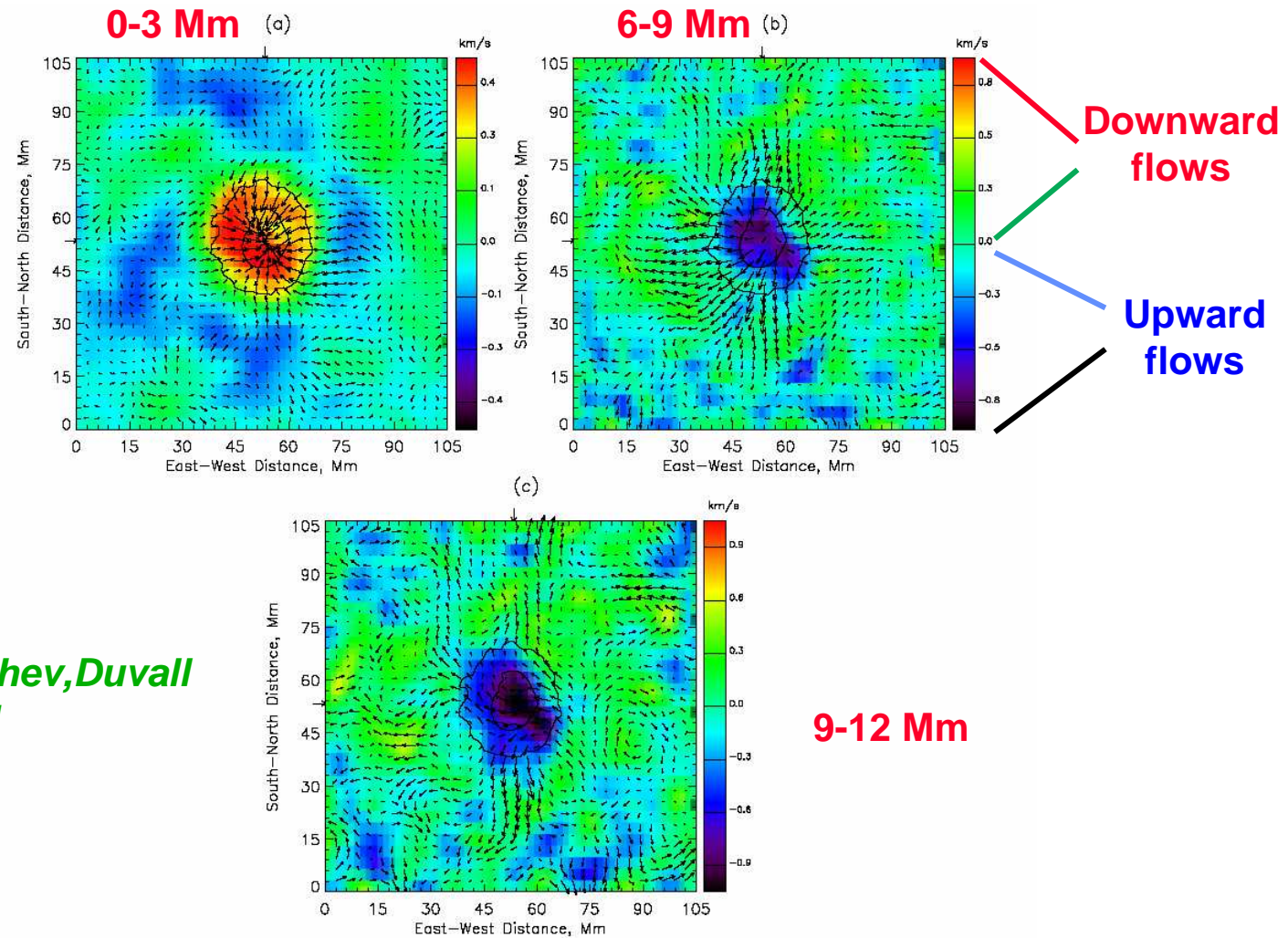
$$\vec{c}_A = \frac{\vec{B}}{\sqrt{4\pi\rho}}$$

- ❑ **Temperature perturbations** => do not depend on the direction of propagation
- ❑ **Flow perturbations** => waves move faster along the flow
- ❑ **Magnetic fields perturbations** => waves traveling perpendicular to the field lines are the most sensitive to B (wave speed anisotropy not yet detected)

Ryutova & Scherrer 1998

Time-distance helioseismology

Results: 3D Flows below sunspot



Zhao, Kosovichev, Duvall
2001

Time-distance helioseismology

Sub sunspot dynamics and structure

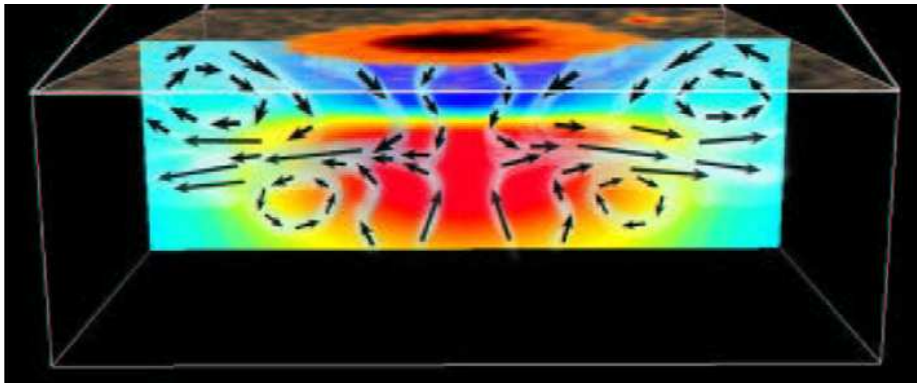
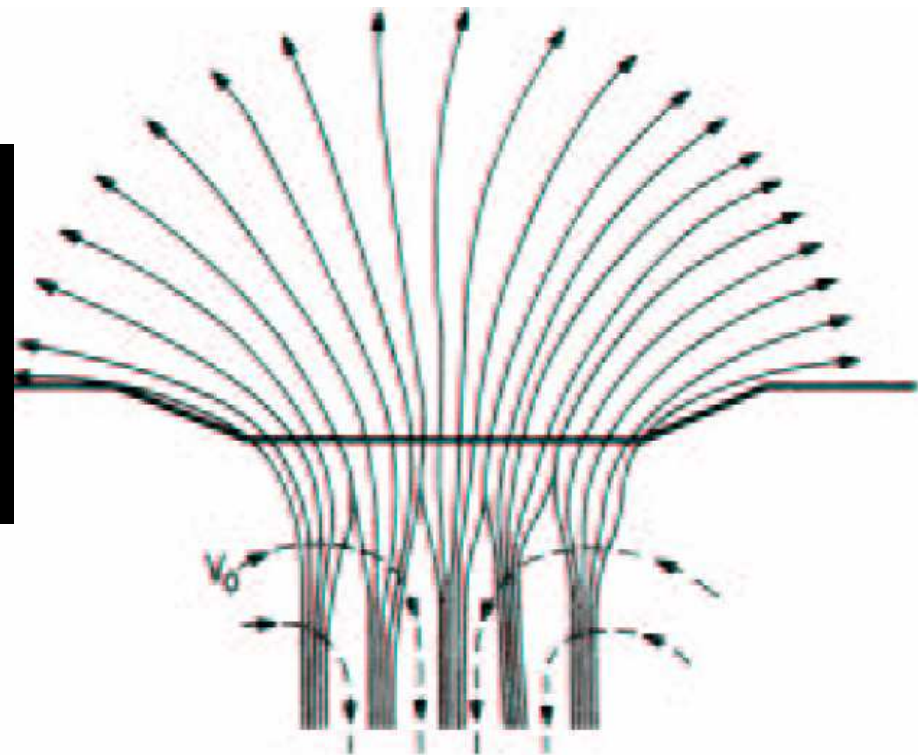


Illustration of sound speed variations and subsurface flow patterns of a sunspot

Courtesy SoHO/MDI



The cluster Model of Sunspot

Parker 1979